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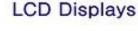


















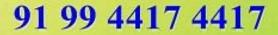


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### 1. General description

The HEF4027B is a edge-triggered dual JK flip-flop which features independent set-direct (SD), clear-direct (CD), clock (CP) inputs and outputs  $(Q, \overline{Q})$ . Data is accepted when CP is LOW, and transferred to the output on the positive-going edge of the clock. The active HIGH asynchronous clear-direct (CD) and set-direct (SD) inputs are independent and override the J, K, and CP inputs. The outputs are buffered for best system performance. Schmitt trigger action makes the clock input highly tolerant of slower rise and fall times.

It operates over a recommended  $V_{DD}$  power supply range of 3 V to 15 V referenced to  $V_{SS}$  (usually ground). Unused inputs must be connected to  $V_{DD}$ ,  $V_{SS}$ , or another input.

# 2. Features and benefits

- Fully static operation
- 5 V, 10 V, and 15 V parametric ratings
- Standardized symmetrical output characteristics
- Specified from –40 °C to +85 °C
- Complies with JEDEC standard JESD 13-B

# 3. Applications

- Registers
- Counters
- Control circuits

# 4. Ordering information

### Table 1. Ordering information

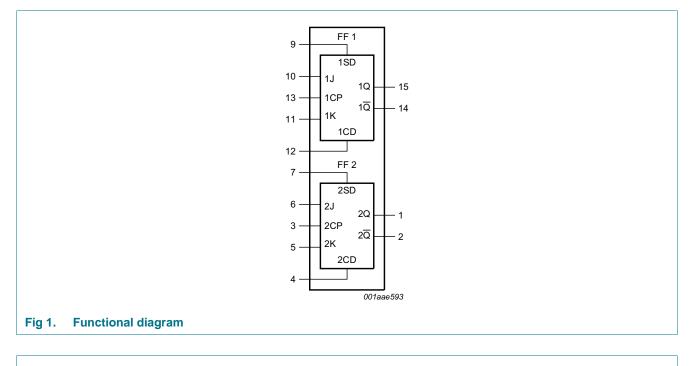
 $T_{amb}$  from -40 °C to +85 °C.

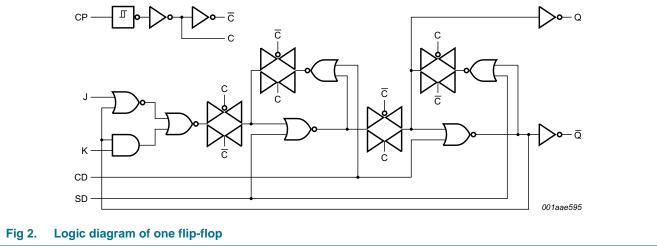
Type number	Package							
	Name	Description	Version					
HEF4027BT	SO16	plastic small outline package; 16 leads; body width 3.9 mm	SOT109-1					



**Dual JK flip-flop** 

# 5. Functional diagram

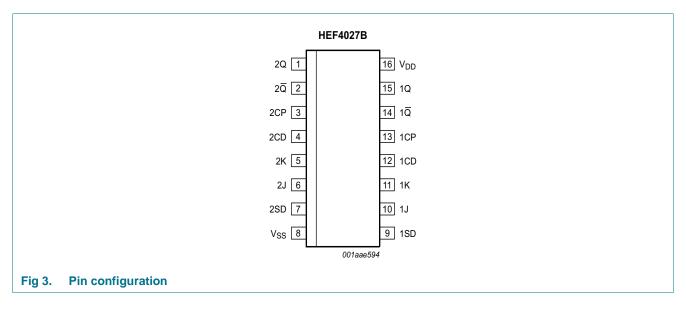




HEF4027B

# 6. Pinning information

# 6.1 Pinning



# 6.2 Pin description

### Table 2.Pin description

Symbol	Pin	Description
V <sub>SS</sub>	8	ground supply voltage
1SD, 2SD	9, 7	asynchronous set-direct input (active HIGH)
1J, 2J	10, 6	synchronous input
1K, 2K	11, 5	synchronous input
1CD, 2CD	12, 4	asynchronous clear-direct input (active HIGH)
1CP, 2CP	13, 3	clock input (LOW-to-HIGH edge-triggered)
1 <u>Q</u> , 2 <u>Q</u>	14, 2	complement output
1Q, 2Q	15, 1	true output
V <sub>DD</sub>	16	supply voltage

# 7. Functional description

### Table 3. Function table<sup>[1]</sup>

Inputs		Outputs				
nSD	nCD	nCP	nJ	nK	nQ	nQ
Н	L	Х	Х	Х	Н	L
L	Н	Х	Х	Х	L	Н
Н	Н	Х	Х	Х	Н	Н
L	L	↑	L	L	no change	no change
L	L	↑	Н	L	Н	L
L	L	1	L	Н	L	Н
L	L	↑	Н	Н	nQ	nQ

[1] H = HIGH voltage level; L = LOW voltage level; X = don't care.;  $\uparrow = positive-going transition.$ 

# 8. Limiting values

### Table 4. Limiting values

In accordance with the Absolute Maximum Rating System (IEC 60134).

Symbol	Parameter	Conditions		Min	Max	Unit
V <sub>DD</sub>	supply voltage			-0.5	+18	V
I <sub>IK</sub>	input clamping current	$V_{I}$ < -0.5 V or $V_{I}$ > $V_{DD}$ + 0.5 V		-	±10	mA
VI	input voltage			-0.5	V <sub>DD</sub> + 0.5	V
I <sub>OK</sub>	output clamping current	$V_{O}$ < -0.5 V or $V_{O}$ > $V_{DD}$ + 0.5 V		-	±10	mA
I <sub>I/O</sub>	input/output current			-	±10	mA
I <sub>DD</sub>	supply current			-	50	mA
T <sub>stg</sub>	storage temperature			-65	+150	°C
T <sub>amb</sub>	ambient temperature	in free air		-40	+85	°C
P <sub>tot</sub>	total power dissipation	T <sub>amb</sub> –40 °C to +85 °C				
		SO16 package	1]	-	500	mW
Р	power dissipation	per output		-	100	mW

[1] For SO16 package: P<sub>tot</sub> derates linearly with 8 mW/K above 70 °C.

# 9. Recommended operating conditions

### Table 5. Recommended operating conditions

Symbol	Parameter	Conditions	Min	Max	Unit
V <sub>DD</sub>	supply voltage		3	15	V
VI	input voltage		0	V <sub>DD</sub>	V
T <sub>amb</sub>	ambient temperature	in free air	-40	+85	°C
$\Delta t / \Delta V$	input transition rise and fall rate	$V_{DD} = 5 V$	-	3.75	μs/V
		V <sub>DD</sub> = 10 V	-	0.5	μs/V
		V <sub>DD</sub> = 15 V	-	0.08	μs/V

# **10. Static characteristics**

### Table 6. Static characteristics

 $V_{SS} = 0$  V;  $V_l = V_{SS}$  or  $V_{DD}$ ; unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	T <sub>amb</sub> =	<b>−40 °C</b>	T <sub>amb</sub> =	25 °C	T <sub>amb</sub> =	85 °C	Unit
				Min	Max	Min	Max	Min	Max	
V <sub>IH</sub>	HIGH-level input voltage	I <sub>O</sub>   < 1 μA	5 V	3.5	-	3.5	-	3.5	-	V
			10 V	7.0	-	7.0	-	7.0	-	V
			15 V	11.0	-	11.0	-	11.0	-	V
V <sub>IL</sub>	LOW-level input voltage	I <sub>O</sub>   < 1 μA	5 V	-	1.5	-	1.5	-	1.5	V
			10 V	-	3.0	-	3.0	-	3.0	V
			15 V	-	4.0	-	4.0	-	4.0	V
V <sub>OH</sub>	HIGH-level output voltage	I <sub>O</sub>   < 1 μA	5 V	4.95	-	4.95	-	4.95	-	V
			10 V	9.95	-	9.95	-	9.95	-	V
			15 V	14.95	-	14.95	-	14.95	-	V
V <sub>OL</sub>	LOW-level output voltage	I <sub>O</sub>   < 1 μA	5 V	-	0.05	-	0.05	-	0.05	V
			10 V	-	0.05	-	0.05	-	0.05	V
			15 V	-	0.05	-	0.05	-	0.05	V
I <sub>OH</sub>	HIGH-level output current	V <sub>O</sub> = 2.5 V	5 V	-	-1.7	-	-1.4	-	-1.1	mA
		V <sub>O</sub> = 4.6 V	5 V	-	-0.52	-	-0.44	-	-0.36	mA
		V <sub>O</sub> = 9.5 V	10 V	-	-1.3	-	-1.1	-	-0.9	mA
		V <sub>O</sub> = 13.5 V	15 V	-	-3.6	-	-3.0	-	-2.4	mA
I <sub>OL</sub>	LOW-level output current	V <sub>O</sub> = 0.4 V	5 V	0.52	-	0.44	-	0.36	-	mA
		$V_{0} = 0.5 V$	10 V	1.3	-	1.1	-	0.9	-	mA
		V <sub>O</sub> = 1.5 V	15 V	3.6	-	3.0	-	2.4	-	mA
l <sub>l</sub>	input leakage current		15 V	-	±0.3	-	±0.3	-	±1.0	μA
I <sub>DD</sub>	supply current	I <sub>O</sub> = 0 A	5 V	-	4.0	-	4.0	-	30	μA
			10 V	-	8.0	-	8.0	-	60	μA
			15 V	-	16.0	-	16.0	-	120	μA
CI	input capacitance		-	-	-	-	7.5	-	-	pF

# **11. Dynamic characteristics**

### Table 7. Dynamic characteristics

 $V_{SS} = 0$  V;  $T_{amb} = 25$  °C; for test circuit see <u>Figure 7</u>; unless otherwise specified.

Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula <sup>[1]</sup>	Min	Тур	Max	Unit
t <sub>PHL</sub>	HIGH to LOW	$CP \rightarrow Q, \overline{Q};$	5 V	78 ns + (0.55 ns/pF)C <sub>L</sub>	-	105	210	ns
	propagation delay	see <u>Figure 4</u>	10 V	29 ns + (0.23 ns/pF)C <sub>L</sub>	-	40	80	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
		$CD \rightarrow Q;$	5 V	93 ns + (0.55 ns/pF)C <sub>L</sub>	-	120	240	ns
		see <u>Figure 4</u>	10 V	33 ns + (0.23 ns/pF)C <sub>L</sub>	-	45	90	ns
			15 V	27 ns + (0.16 ns/pF)C <sub>L</sub>	-	35	70	ns
		$SD \rightarrow \overline{Q};$	5 V	113 ns + (0.55 ns/pF)C <sub>L</sub>	-	140	280	ns
		see Figure 4	10 V	44 ns + (0.23 ns/pF)C <sub>L</sub>	-	55	110	ns
			15 V	32 ns + (0.16 ns/pF)C <sub>L</sub>	-	40	80	ns
t <sub>PLH</sub>	LOW to HIGH	$CP \rightarrow Q, \overline{Q};$	5 V	58 ns + (0.55 ns/pF)C <sub>L</sub>	-	85	170	ns
	propagation delay	see Figure 4	10 V	27 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	22 ns + (0.16 ns/pF)C <sub>L</sub>	-	30	60	ns
		$CD \rightarrow \overline{Q};$	5 V	48 ns + (0.55 ns/pF)C <sub>L</sub>	-	75	150	ns
		see Figure 4	10 V	24 ns + (0.23 ns/pF)C <sub>L</sub>	-	35	70	ns
			15 V	17 ns + (0.16 ns/pF)C <sub>L</sub>	-	25	50	ns
		$SD \rightarrow Q;$	5 V	43 ns + (0.55 ns/pF)C <sub>L</sub>	-	70	140	ns
		see Figure 4	10 V	19 ns + (0.23 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	17 ns + (0.16 ns/pF)C <sub>L</sub>	-	25	50	ns
tt	transition time	see Figure 4	5 V [2]	10 ns + (1.00 ns/pF)C <sub>L</sub>	-	60	120	ns
			10 V	9 ns + (0.42 ns/pF)C <sub>L</sub>	-	30	60	ns
			15 V	6 ns + (0.28 ns/pF)C <sub>L</sub>	-	20	40	ns
t <sub>su</sub>	set-up time	$J,K\toCP;$	5 V		50	25	-	ns
		see <u>Figure 5</u>	10 V		30	10	-	ns
			15 V		20	5	-	ns
t <sub>h</sub>	hold time	$J,K\toCP;$	5 V		25	0	-	ns
		see <u>Figure 5</u>	10 V		20	0	-	ns
			15 V		15	5	-	ns
t <sub>W</sub>	pulse width	CP LOW;	5 V		80	40	-	ns
		minimum width see Figure 5	10 V		30	15	-	ns
		see <u>Figure 5</u>	15 V		24	12	-	ns
		SD, CD HIGH;	5 V		90	45	-	ns
		minimum width	10 V		40	20	-	ns
		see <u>Figure 6</u>	15 V		30	15	-	ns
t <sub>rec</sub>	recovery time	SD, CD inputs;	5 V		+20	-15	-	ns
		see <u>Figure 6</u>	10 V		+15	-10	-	ns
			15 V		+10	-5	-	ns

**Dual JK flip-flop** 

$V_{\rm SS} = 0 V$	$V_{SS} = 0 V$ ; $T_{amb} = 25 C$ ; for test circuit see <u>Figure 7</u> ; unless otherwise specified.										
Symbol	Parameter	Conditions	V <sub>DD</sub>	Extrapolation formula <sup>[1]</sup>	Min	Тур	Max	Unit			
f <sub>max</sub>	maximum	CP input;	5 V		4	8	-	MHz			
	frequency	J = K = HIGH; see <u>Figure 5</u>	10 V		12	25	-	MHz			
		see <u>rigure s</u>	15 V		15	30	-	MHz			

#### Table 7. Dynamic characteristics ... continued

[1] The typical values of the propagation delay and transition times are calculated from the extrapolation formulas shown (C<sub>L</sub> in pF).

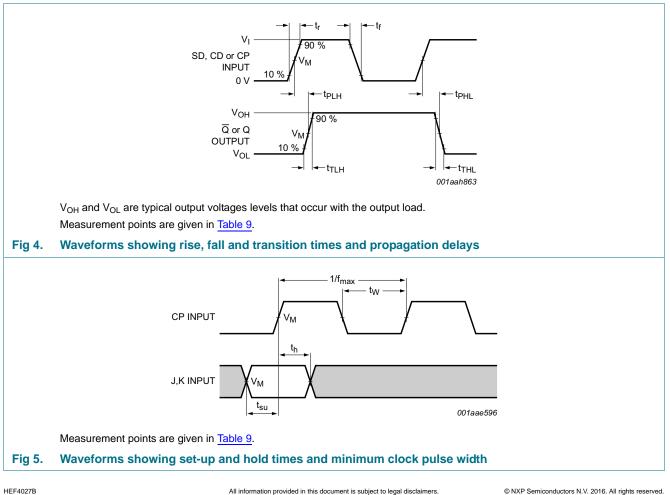
[2]  $t_t$  is the same as  $t_{TLH}$  and  $t_{THL}$ .

#### Table 8. Dynamic power dissipation P<sub>D</sub>

 $P_D$  can be calculated from the formulas shown.  $V_{SS} = 0$  V;  $t_r = t_f \le 20$  ns;  $T_{amb} = 25$  °C.

Symbol	Parameter	V <sub>DD</sub>	Typical formula for $P_D$ ( $\mu$ W)	Where:
PD	dynamic power	5 V	$P_D = 900 \times f_i + \Sigma(f_o \times C_L) \times V_DD^2$	f <sub>i</sub> = input frequency in MHz;
	dissipation	10 V	$P_{D} = 4500 \times f_{i} + \Sigma (f_{o} \times C_{L}) \times V_{DD}^{2}$	$f_o = output frequency in MHz;$
		15 V	$P_{D} = 13200 \times f_{i} + \Sigma(f_{o} \times C_{L}) \times V_{DD}^{2}$	$C_L$ = output load capacitance in pF;
				V <sub>DD</sub> = supply voltage in V;
				$\Sigma(f_o \times C_L)$ = sum of the outputs.

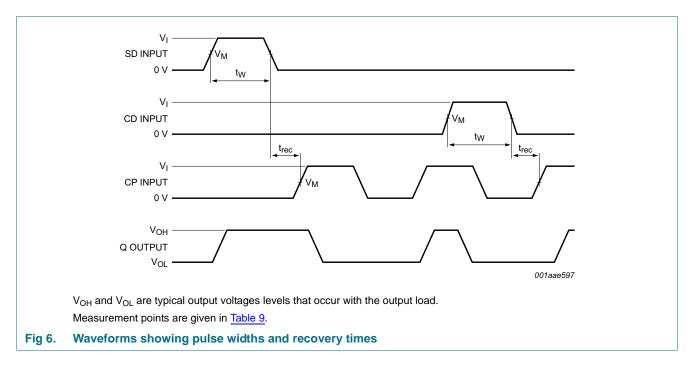
# 12. Waveforms



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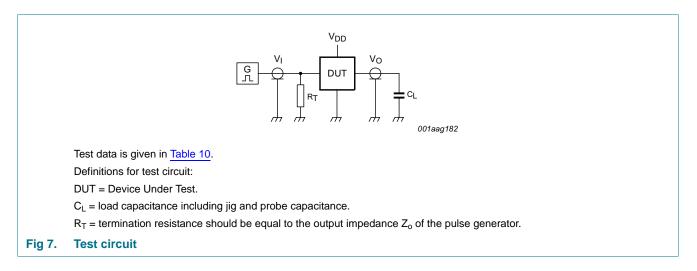
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**Dual JK flip-flop** 



### Table 9. Measurement points

Supply voltage	Input	Output
V <sub>DD</sub>	V <sub>M</sub>	V <sub>M</sub>
5 V to 15 V	0.5V <sub>DD</sub>	0.5V <sub>DD</sub>



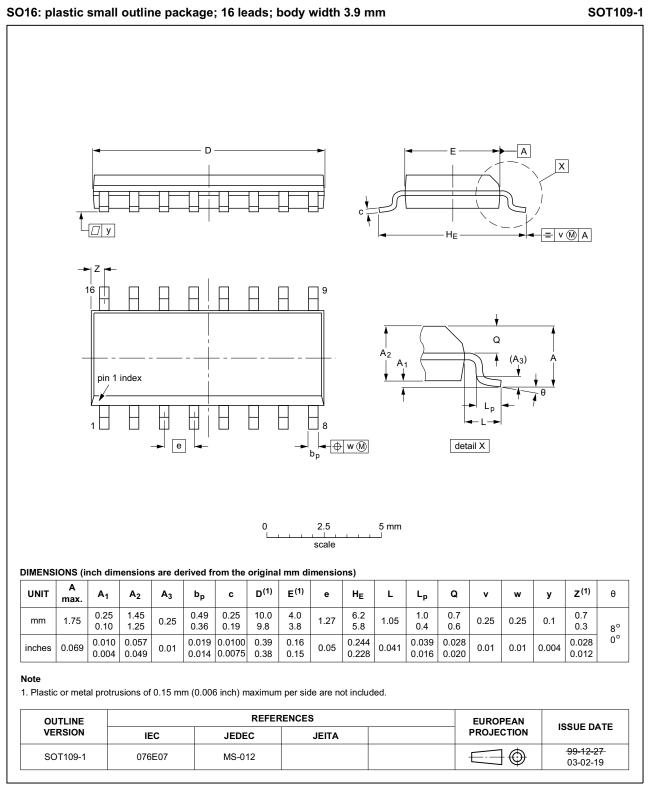
### Table 10. Test data

Supply voltage	Input	Load	
V <sub>DD</sub>	VI	t <sub>r</sub> , t <sub>f</sub>	CL
5 V to 15 V	$V_{SS}$ or $V_{DD}$	≤ 20 ns	50 pF

HEF4027B Product data sheet

**Dual JK flip-flop** 

# 13. Package outline



### Fig 8. Package outline SOT109-1 (SO16)

HEF4027B

# 14. Revision history

### Table 11.Revision history

Document ID	Release date	Data sheet status	Change notice	Supersedes
HEF4027B v.10	20160321	Product data sheet	-	HEF4027B v.9
Modifications:	Type number	HEF4027BP (SOT38-4) remov	ved.	
HEF4027B v.9	20111118	Product data sheet	-	HEF4027B v.8
Modifications:	<ul> <li>Legal pages (</li> </ul>	updated.		
	<ul> <li>Changes in "Control</li> </ul>	General description" and "Feat	ures and benefits".	
HEF4027B v.8	20111010	Product data sheet	-	HEF4027B v.7
HEF4027B v.7	20091125	Product data sheet	-	HEF4027B v.6
HEF4027B v.6	20090624	Product data sheet	-	HEF4027B v.5
HEF4027B v.5	20081110	Product data sheet	-	HEF4027B v.4
HEF4027B v.4	20080703	Product specification	-	HEF4027B_CNV v.3
HEF4027B_CNV v.3	19950101	Product specification	-	HEF4027B_CNV v.2
HEF4027B_CNV v.2	19950101	Product specification	-	-

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HEF4027B

### **Dual JK flip-flop**

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**Dual JK flip-flop** 

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